

# Jefferson Pardomuan

· PHD IN COMPUTER SCIENCE

42 Beauford st Huntingdale Vic 3166,

☎ +61 0466-983-637 | ✉ jefferson.pardomuan@gmail.com | 🌐 <https://www.linkedin.com/in/jefferson-pardomuan/>

## Education

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### Tokyo Institute of Technology

Tokyo, Japan

PH.D COMPUTER SCIENCE

10/2020-9/2023

- Advisor: Prof. Hideki Koike
- Thesis: Shape-changing and Variable-stiffness Interface using Pneumatic Actuator

### University of Electro-communication Tokyo

Tokyo, Japan

M.ENG. INFORMATION SYSTEM

4/2012-3/2014

- Advisor: Prof. Hideki Koike
- Thesis: Variable-stiffness Deformable Interface using Vacuum Jamming

### Polytechnic University Japan

Kanagawa, Japan

B.ENG.(HONS) ELECTRONIC SYSTEM

4/2008-3/2012

- Minors in Vocational Training Instructor

## Professional Experience

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- 2023-2024 **Postdoctoral research fellow**, Tokyo Institute of Technology (Tokyo)
- 2019-2020 **Business Development Manager**, Pratama Graha Semesta Co. (Jakarta)
- 2015-2018 **Senior Process Engineer**, Sumitomo Electric Indonesia (Jakarta)
- 2014-2015 **Process Engineer**, Sumitomo Electric Japan (Osaka)

## Publications

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### JOURNAL

- J. Pardomuan**, N. Takahashi and H. Koike, "ASTRE: Prototyping Technique for Modular Soft Robots With Variable Stiffness," in IEEE Access, vol. 10, pp. 80495-80504, 2022, doi: 10.1109/ACCESS.2022.3194887.
- T. Sato, **J. Pardomuan**, Y. Matoba and H. Koike, "ClaytrixSurface: An Interactive Deformable Display with Dynamic Stiffness Control," in IEEE Computer Graphics and Applications, vol. 34, no. 3, pp. 59-67, May-June 2014, doi: 10.1109/MCG.2014.39.

### PRESENTATION

- J. Pardomuan**, S. Miyafuji, N. Takahashi and H. Koike, "VabricBeads : Variable Stiffness Structured Fabric using Artificial Muscle in Woven Beads", In Proceedings of CHI '24. May, 2024, Hawaii, US. 17 pages (Accept with minor revision)

### CONTRIBUTED PRESENTATION

- D. Saito, E. Nagatomo, **J. Pardomuan**, H. Koike, "Tracker: Model-Based Reinforcement Learning for Tracking Control of Human Finger Attached with Thin McKibben Muscles" In Proceedings of IEEE RO-MAN'23. Augustus, 2023, Busan, Korea. Accepted
- L. Takagi, S. Miyafuji, **J. Pardomuan**, and H. Koike. "LUNACHair: Remote Wheelchair System Linking Users to Nearby People and Assistants." In Proceedings of AHs '23. March, 2023, Glasgow, UK. <https://doi.org/10.1145/3582700.3582714>
- J. Hoffard, S. Miyafuji, **J. Pardomuan**, T. Sato, and H. Koike, "OmniTiles: A User-Customizable Display Using An Omni-Directional Camera Projector System." In Proceedings of ICAT-EGVE 2022, November, 2022, Yokohama, Japan.

### DEMO/POSTER PRESENTATION

**J. Pardomuan**, N. Takahashi and H. Koike. "ASTREL: Prototyping Shape-changing Interface with Variable Stiffness Soft Robotics Module". In Adjunct Proceedings of UIST '22, October, 2022, Bend, OR, US. <https://doi.org/10.1145/3526114.3558733>

L. Takagi, S. Miyafuji, **J. Pardomuan**, and H. Koike. "LUNACHair: Remote Wheelchair System that Links Up a Remote Care-giver and Wheelchair Surroundings. In Adjunct Proceedings of UIST '22, October, 2022, Bend, OR, US.

J. Hoffard, S. Miyafuji, **J. Pardomuan**, T. Sato, and H. Koike. "FroggyHand: A Gesture Based Control System for Omni-Directional Projections." In Adjunct Proceedings of AHs '22, March, 2022 Chiba, JP. <https://doi.org/10.1145/3519391.3524027>

**J. Pardomuan**, T. Sato, and H. Koike. "LivingClay: particle actuation to control display volume and stiffness." In Adjunct Proceedings of UIST '13. October, 2022, St. Andrews, Scotland, UK <https://doi.org/10.1145/2508468.2514731>

## IN PREP

**J. Pardomuan**, S. Miyafuji, N. Takahashi and H. Koike, "Constructive Assembly Tools for Shape-changing and Variable Stiffness Interface", 11 pages.

## Awards, Fellowships, & Grants

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- 2023 **Interaction Interactive Demo Award**, Interaction IPSJ2023, Tokyo, Japan
- 2020-2023 **MEXT Japan**, Scholarship Recipient
- 2013-2014 **East Asian Circle of Applied Technology Foundation**, Scholarship Recipient
- 2007-2012 **Japan Ministry of Health, Labour, and Welfare**, Scholarship Recipient

## Teaching Experience

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- Fall 2022 **Data Structure and Algorithm**, Teaching Assistant
- Fall 2021 **Data Structure and Algorithm**, Teaching Assistant
- Spring 2022 **Procedural Programming Fundamentals**, Teaching Assistant
- Fall 2020 **Human Computer Interaction**, Teaching Assistant

## Advising

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- 2022-2023 **Luna Takagi**, Master of Engineering in Computer Science
- 2022-2023 **Eri Nagatomo**, Bachelor of Engineering in Computer Science
- 2021-2022 **Jana Howard**, Master of Engineering in Computer Science

## Referees

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### **Prof. Hideki Koike**

PROFESSOR OF COMPUTER SCIENCE  
koike@c.titech.ac.jp

+81 337261111

*Tokyo Institute of Technology*

PhD and Master degree main supervisor

### **Prof. Toshiki Sato**

ASSOCIATE PROFESSOR  
tsato@jaist.ac.jp

+81 761511111

*Japan Advanced Institute of  
Science and Technology*

Master degree co-supervisor

### **Dr. Shio Miyafuji**

ASSISTANT PROFESSOR  
miyafuji@c.titech.ac.jp

+81 337261111

*Tokyo Institute of Technology*

PhD research mentor and collaborator

## Professional Memberships

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2023-2024 **ACM Special Interest Group on Computer-Human Interaction**, SIGCHI

## Licence and Certification

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2009 **Japanese-Language Proficiency Test (JLPT)**, N1

2012 **Vocational Training Instructor Licence**, Electronic and Computer Control

## Skills

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### PROGRAMMING LANGUAGE

- Python, C/C++, C#, Matlab

### PLATFORMS & TOOLS

- TensorFlow, Unity, Visual Studio, Xcode, Android Studio

### LANGUAGES

- Indonesian (native), Japanese (N1), English (Proficient)

### HARDWARE & DESIGN

- Arduino, PCB, CAD, Digital Fabrication, Soft robotics, Pneumatic systems, Manufacturing technology